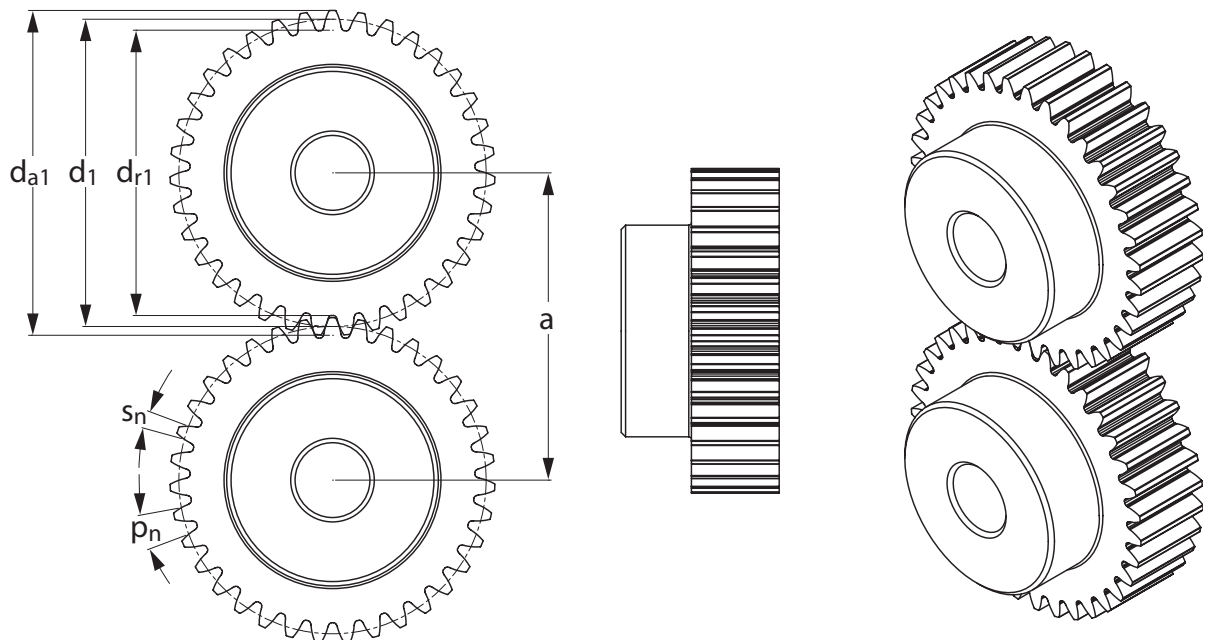


Description	Symbol	Unit	Equation
Normal Module	$m_n$		
Transverse Module	$m_t$		$= m_n$
Normal Pressure Angle	$\alpha_n$	degrees	$= 20^\circ$
Transverse Pressure Angle	$\alpha_t$	degrees	$= \alpha_n$
Number of Teeth	$z$		
Profile Shift Coefficient	$x$		$=$ zero for Ondrives standard gears
Addendum	$h_a$	mm	$= 1.00 \cdot m_n$ (for Ondrives standard gears)
Dedendum	$h_f$	mm	$= 1.25 \cdot m_n$ (for Ondrives standard gears)
Tooth Depth	$h$	mm	$= 2.25 \cdot m_n$ (for Ondrives standard gears)
Gear Ratio	$u$		$= z_2 / z_1$
Centre Distance	$a$	mm	$= (d_1 + d_2) / 2$
Pitch Circle Diameter	$d$	mm	$= z \cdot m_n$
Tip Diameter	$d_a$	mm	$= d + (2m_n \cdot x) + (2 \cdot m_n)$
Root Diameter	$d_r$	mm	$= d_a - (2 \cdot h)$
Normal Pitch	$p_n$	mm	$= \pi \cdot m_n$
Normal Tooth Thickness in Pitch Circle	$s_n$	mm	$= (p_n / 2) + 2m_n \cdot x \cdot \tan \alpha_n$

When working with a pair of gears the subscript **1** and **2** denotes input (drive) and output (driven) gear. Tip diameter is the theoretical diameter of the gear without tooth thickness tolerance applied. For  $s_n$  when  $x =$  zero, this is the theoretical tooth thickness. Actual tooth thickness will be less. The subscript **e** is for upper allowance values and **i** for lower allowance values.



### Gear Quality

Standard metal gears are supplied to quality Grade 7 DIN 3961 based on Pitch total deviation  $F_p$ , Pitch deviation  $f_p$ , Radial runout  $F_r$  and Pitch error  $f_u$ . Skive hobbed gears are supplied to quality Grade 6 DIN 3961.

GG25 Cast Iron, PEEK GF30<sup>®</sup> and Delrin (POM) are supplied to quality Grade 8 DIN 3961.

Ondrives can manufacture gears to higher grades on request. Ondrives can offer testing certification for a gear's individual parameters using the latest CMM machine with gear measuring software.

Double and single flank testing is available on request. Please contact our technical department for details.

### Comparisons of Grade Standards

Example 3 mod, 50 teeth, 30mm face width spur gear.

	Standard Grade	DIN 3961 6	DIN 3961 7	ISO 1328 7	AGMA 10
Pitch total deviation	$F_p$ $\mu\text{m}$	32	44	50	51
Pitch deviation	$f_p$ $\mu\text{m}$	8	12	13	13
Radial runout	$F_r$ $\mu\text{m}$	22	31	40	41
Pitch error	$f_u$ $\mu\text{m}$	10	15	-	-
Double flank composite transmission error	$F_i''$ $\mu\text{m}$	26	36	61	61
Double flank tooth-to-tooth transmission error	$f_i''$ $\mu\text{m}$	11	15	21	20

### Torque

Stated value for metal spur gears is maximum torque ( $T_2$ ) based on two identical gears with the same number of teeth running at standard centres. Value is minimum from surface stress or bending stress.

Other factors including duty cycle and temperature will affect maximum allowable torque and service life.

Wear is dependant on lubrication. We recommend that each user compute their own values based on actual operating conditions and test in application.

Materials	817M40	805M20	303 Stainless	316 Stainless	GG25 Cast Iron
Input Speed	100 rpm Uniform, 12 hours running per day				
Bending Stress Factor $S_b$	32,000	50,000	20,000	15,800	7,600
Surface Stress Factor $S_c$	3,000	11,000	1,800	1,400	1,350

Stated value for plastic spur gears is maximum torque ( $T_2$ ) based on two identical gears with the same number of teeth running at standard centres. Value is minimum from surface stress, bending stress or bulk/surface temperature using method from BS 6168:1987.

The torque capacity of plastic gears is highly dependant on operating condition. All values are reference only.

We recommend that each user test in application under specific operation conditions of application.

Materials	Delrin POM (White)	PEEK GF30 <sup>®</sup> (Light Brown)
Input Speed / No. of Load Cycles	100 rpm / $10^8$	100 rpm / $10^8$
Limiting Bending Stress	22.0 N/mm <sup>2</sup>	30 N/mm <sup>2*</sup>
Limiting Surface Stress	22.0 N/mm <sup>2</sup>	80 N/mm <sup>2*</sup>
Initial Temperature	20°C	20°C
Max. Bulk or Surface Temperature	60°C	80°C
Coefficient of Friction	0.18 (Dry)	0.25**

\* Reference Only \*\* Approximate value based on initial light greasing.

Maximum torque for titanium gears is approximately 30% of 817M40 steel gears.

Due to lack of stress factors we are unable to offer specific values. Testing in application is required.

Torque for anti-backlash spur gears is limited by the spring rating. Please contact our Technical department for details.

When selecting gears application factors should be applied to required torque.

$T_2 > T_{\text{required}} \times K_a$  Application factor  $K_a$

Working characteristics of driving machine	Working characteristics of driven machine			
	Uniform	Light Shocks	Moderate Shocks	Heavy Shocks
Uniform	1.00	1.25	1.50	1.75
Light Shocks	1.10	1.35	1.60	1.85
Moderate Shocks	1.25	1.50	1.75	2.00
Heavy Shocks	1.50	1.75	2.00	2.25+

Description	Symbol	Unit	Equation
Normal Module	$m_n$		
Transverse Module	$m_t$		$= m_n / \cos \beta$
Axial Module	$m_x$		$= m_n / \sin \beta$
Normal Pressure Angle	$\alpha_n$	degrees	$= 20^\circ$
Transverse Pressure Angle	$\alpha_t$	degrees	$= \tan^{-1} (\tan \alpha_n / \cos \beta)$
Helix Angle	$\beta$	degrees	$= 15^\circ$
Lead Angle	$\lambda$	degrees	$= 90 - \beta$
Number of Teeth	$z$		
Profile Shift Coefficient	$x$		$=$ zero for Ondrives standard gears
Addendum	$h_a$	mm	$= 1.00 \cdot m_n$ (for Ondrives standard gears)
Dedendum	$h_f$	mm	$= 1.25 \cdot m_n$ (for Ondrives standard gears)
Tooth Depth	$h$	mm	$= 2.25 \cdot m_n$ (for Ondrives standard gears)
Gear Ratio	$u$		$= z_2 / z_1$
Centre Distance	$a$	mm	$= (d_1 + d_2) / 2$
Pitch Circle Diameter	$d$	mm	$= z \cdot m_t = (z \cdot m_n) / \cos \beta$
Tip Diameter	$d_a$	mm	$= d + (2m_n \cdot x) + (2 \cdot m_n)$
Root Diameter	$d_r$	mm	$= d_a - (2 \cdot h)$
Normal Pitch	$p_n$	mm	$= \pi \cdot m_n$
Transverse Pitch	$p_t$	mm	$= \pi \cdot m_t = (\pi \cdot m_n) / \cos \beta$
Axial Pitch	$p_x$	mm	$= \pi \cdot m_x = (\pi \cdot m_n) / \sin \beta$
Normal Tooth Thickness in Pitch Circle	$s_n$	mm	$= (p_n / 2) + 2m_n \cdot x \cdot \tan \alpha_n$
Transverse Tooth Thickness in Pitch Circle	$s_t$	mm	$= (p_t / 2) + 2m_n \cdot x \cdot \tan \alpha_t = S_n / \cos \beta$

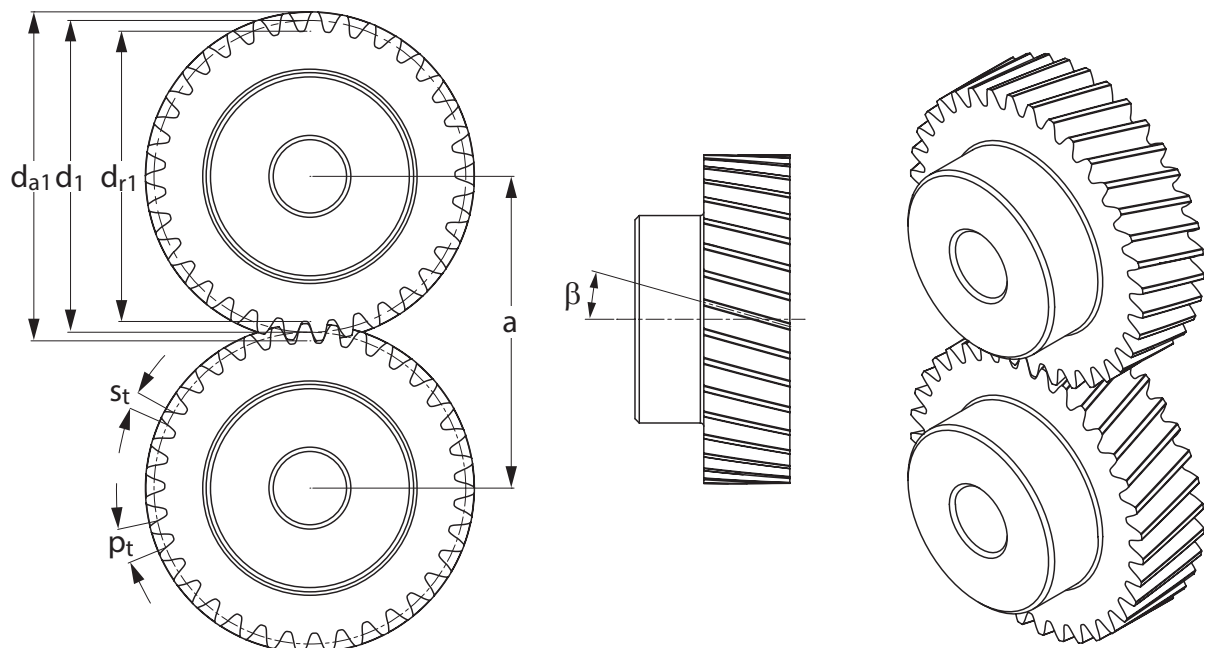
When working with a pair of gears the subscript **1** and **2** denotes input (drive) and output (driven) gear.

Tip diameter is the theoretical diameter of the gear without tooth thickness tolerance applied.

For  $s_n$  &  $s_t$  when  $x =$  zero, this is the theoretical tooth thickness. Actual tooth thickness will be less.

The subscript **e** is for upper allowance values and **i** for lower allowance values.

For two helical gears to run together one must be left hand and the other right hand helix.



### Gear Quality

Standard gears are supplied to quality grade 7e25 DIN 3961 based on the following parameters

$$\text{Radial Runout } F_r = \left( \left( 1.68 + 2.18\sqrt{m_n} + (2.3 + 1.2 \log m_n) \cdot d^{1/4} \right) \cdot 1.4 \right) \cdot 1.4$$

$$\text{Pitch Deviation } f_p = \left( \left( 4 + 0.315(m_n + 0.25\sqrt{d}) \right) \cdot 1.4 \right) \cdot 1.4$$

$$\text{Total Pitch Deviation } F_p = \left( \left( 7.25 \cdot \frac{d^{1/3}}{z^{1/7}} \right) \cdot 1.4 \right) \cdot 1.4$$

$$\text{Pitch Error } f_u = \left( \left( 5 + 0.4(m_n + 0.25\sqrt{d}) \right) \cdot 1.4 \right) \cdot 1.4$$

Ondrives manufacture gears to higher quality grades on request. Ondrives can offer testing certification of a gears individual parameters using the latest CMM machine with gear measuring software. Double and single flank testing is available on request. Please contact our technical department for details.

### Comparisons of Grade Standards

Example 3 mod, 50 teeth, 30mm face width 15° helix parallel helical gear.

	Standard Grade	DIN 3961 7	ISO 7	AGMA 10
Pitch total deviation	$F_p$ µm	47	50	55
Pitch deviation	$f_p$ µm	12	13	12
Radial runout	$F_r$ µm	31	40	44
Pitch error	$f_u$ µm	15	-	-
Double flank composite transmission error	$F_i''$ µm	36	61	65
Double flank tooth-to-tooth transmission error	$f_i''$ µm	15	21	20

### Torque

Stated value for metal spur gears is maximum torque ( $T_2$ ) based on two identical gears with the same number of teeth running at standard centres. Value is minimum from surface stress or bending stress.

Other factors including duty cycle and temperature will affect maximum allowable torque and service life.

Wear is dependant on lubrication. We recommend that each user compute their own values based on actual operating conditions and test in application.

Materials	817M40	805M20	303 Stainless	316 Stainless
Input Speed	100 rpm Uniform, 12 hours running per day			
Bending Stress Factor $S_b$	32,000	50,000	20,000	15,800
Surface Stress Factor $S_c$	3,000	11,000	1,800	1,400

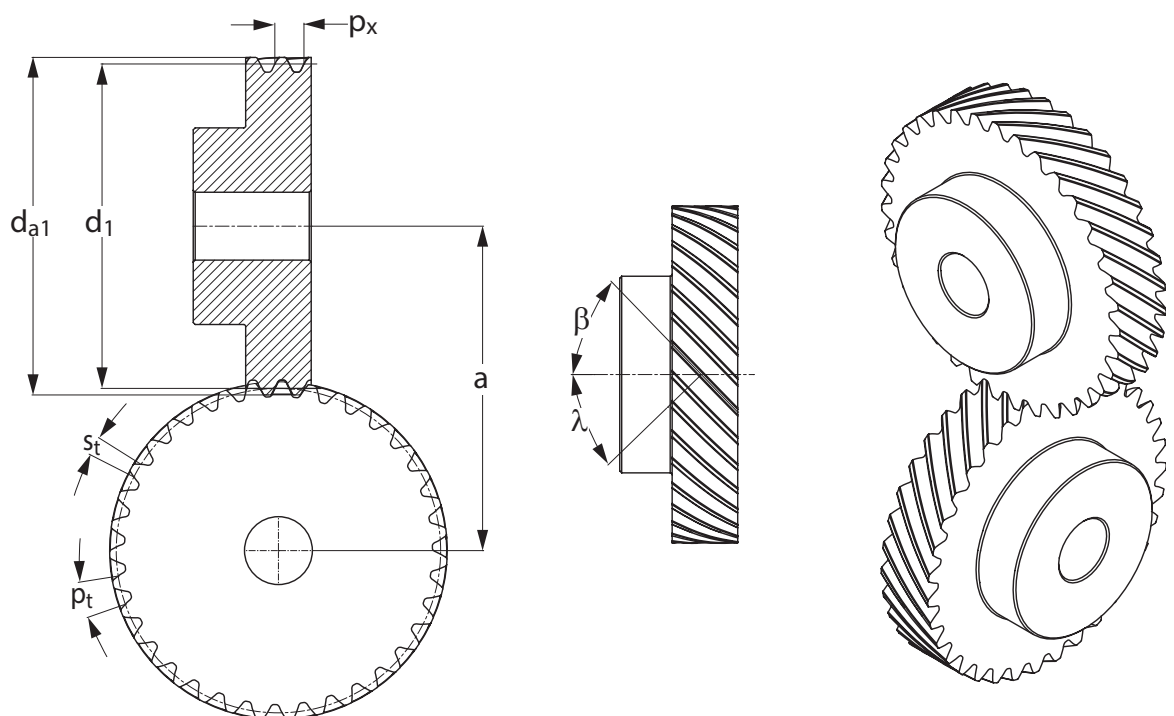
When selecting gears application factors should be applied to required torque.

$$T_2 > T_{\text{required}} \times K_a \quad \text{Application factor } K_a$$

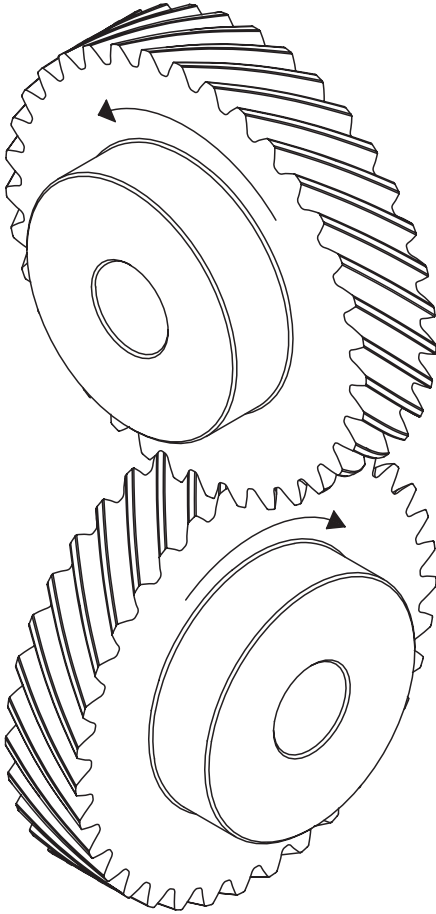
Working characteristics of driving machine	Working characteristics of driven machine			
	Uniform	Light Shocks	Moderate Shocks	Heavy Shocks
Uniform	1.00	1.25	1.50	1.75
Light Shocks	1.10	1.35	1.60	1.85
Moderate Shocks	1.25	1.50	1.75	2.00
Heavy Shocks	1.50	1.75	2.00	2.25+

Description	Symbol	Unit	Equation
Normal Module	$m_n$		
Transverse Module	$m_t$		$= m_n / \cos \beta$
Axial Module	$m_x$		$= m_n / \sin \beta$
Normal Pressure Angle	$\alpha_n$	degrees	$= 20^\circ$
Transverse Pressure Angle	$\alpha_t$	degrees	$= \tan^{-1} (\tan \alpha_n / \cos \beta)$
Helix Angle	$\beta$	degrees	$= 45^\circ$
Lead Angle	$\lambda$	degrees	$= 90 - \beta$
Number of Teeth	$z$		
Profile Shift Coefficient	$x$		$=$ zero for Ondrives standard gears
Addendum	$h_a$	mm	$= 1.00 \cdot m_n$ (for Ondrives standard gears)
Dedendum	$h_f$	mm	$= 1.25 \cdot m_n$ (for Ondrives standard gears)
Tooth Depth	$h$	mm	$= 2.25 \cdot m_n$ (for Ondrives standard gears)
Gear Ratio	$u$		$= z_2 / z_1$
Centre Distance	$a$	mm	$= (d_1 + d_2) / 2$
Pitch Circle Diameter	$d$	mm	$= z \cdot m_t = (z \cdot m_n) / \cos \beta$
Tip Diameter	$d_a$	mm	$= d + (2m_n \cdot x) + (2 \cdot m_n)$
Root Diameter	$d_r$	mm	$= d_a - (2 \cdot h)$
Normal Pitch	$p_n$	mm	$= \pi \cdot m_n$
Transverse Pitch	$p_t$	mm	$= \pi \cdot m_t = (\pi \cdot m_n) / \cos \beta$
Axial Pitch	$p_x$	mm	$= \pi \cdot m_x = (\pi \cdot m_n) / \sin \beta$
Normal Tooth Thickness in Pitch Circle	$s_n$	mm	$= (p_n / 2) + 2m_n \cdot x \cdot \tan \alpha_n$
Transverse Tooth Thickness in Pitch Circle	$s_t$	mm	$= (p_t / 2) + 2m_n \cdot x \cdot \tan \alpha_t$

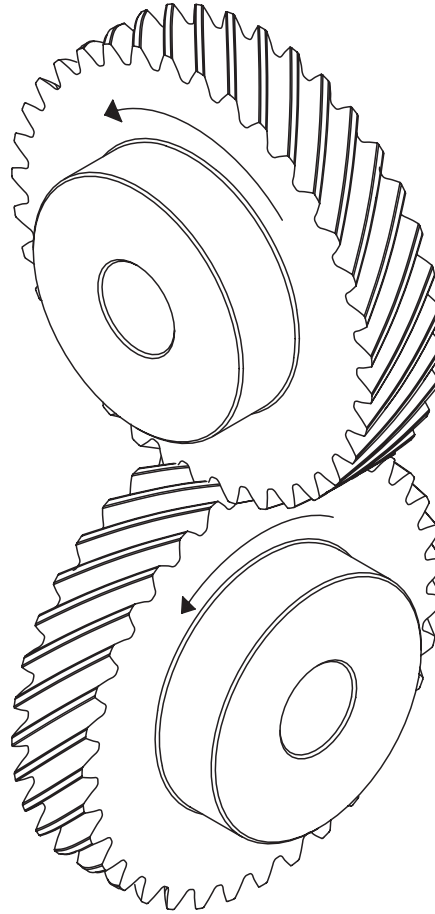
When working with a pair of gears the subscript **1** and **2** denotes input (drive) and output (driven) gear.  
 Tip diameter is the theoretical diameter of the gear without tooth thickness tolerance applied.  
 For  $s_n$  &  $s_t$  when  $x =$  zero, this is the theoretical tooth thickness. Actual tooth thickness will be less.  
 The subscript **e** is for upper allowance values and **i** for lower allowance values.  
 For two crossed axis helical gears to run together both must be right hand or left hand helix.



### Direction of Rotation



**Right Hand Helix**



**Left Hand Helix**

### Torque

Stated value is maximum torque ( $T_2$ ) based on two identical gears with the same number of teeth running at standard centres.

Crossed axis helical gears transmit load by point contact. The limiting condition is typically surface stress. Other factors including duty cycle and temperature will affect maximum allowable torque and service life. Wear is dependant on lubrication.

We recommend that each user compute their own values based on actual operating conditions and test in application.

Materials	817M40	805M20 (SAE 8620) Case Hardened
Input Speed	100 rpm uniform speed	
Bending Stress Factor $S_b$	32,000	50,000
Surface Stress Factor $S_c$	3,000	11,000
Lubrication	Mineral Oil	
Lubrication Viscosity	Between 60mm <sup>2</sup> /s and 130mm <sup>2</sup> /s at 60°C	

When selecting gears application factors should be applied to required torque.

$$T_2 > T_{\text{required}} \times K_a \quad \text{Application factor } K_a$$

Working characteristics of driving machine	Working characteristics of driven machine			
	Uniform	Light Shocks	Moderate Shocks	Heavy Shocks
Uniform	1.00	1.25	1.50	1.75
Light Shocks	1.10	1.35	1.60	1.85
Moderate Shocks	1.25	1.50	1.75	2.00
Heavy Shocks	1.50	1.75	2.00	2.25+

Description	Symbol	Unit	Equation
Axial Module	$m_x$		
Normal Module	$m_n$		$= m_x \cdot \cos \lambda$
Normal Pressure Angle	$\alpha_n$	degrees	$= 20^\circ$
Transverse Pressure Angle	$\alpha_t$	degrees	$= \tan^{-1} (\tan \alpha_n / \cos \lambda)$
Lead Angle	$\lambda$	degrees	$= \tan^{-1} ((m_x \cdot z_1) / d_1)$
Helix Angle	$\beta$	degrees	$= 90 - \lambda$
Number of Starts on Worm	$z_1$		
Number of Teeth on Wheel	$z_2$		
Profile Shift Coefficient	$x$		$=$ zero for Ondrives standard worms
Addendum	$h_a$	mm	$= 1.00 \cdot m_x$ (for Ondrives standard worms)
Dedendum	$h_f$	mm	$= 1.25 \cdot m_x$ (for Ondrives standard worms)
Tooth Depth	$h$	mm	$= 2.25 \cdot m_x$ (for Ondrives standard worms)
Gear Ratio	$u$		$= z_2 / z_1$
Centre Distance	$a$	mm	$= (d_1 + d_2) / 2$
Reference Diameter of Worm	$d_1$	mm	$= (m_x \cdot z_1) / \tan \lambda$
Reference Diameter of Wheel	$d_2$	mm	$= m_x \cdot z_2$
Tip Diameter of Worm	$d_{a1}$	mm	$= d_1 + (2 \cdot m_x)$
Root Diameter of Worm	$d_{r1}$	mm	$= d_{a1} - (2 \cdot h)$
Tip Diameter of Wheel	$d_{a2}$	mm	$= d_2 + (2 \cdot m_x)$
Root Diameter of Wheel	$d_{r2}$	mm	$= d_{a2} - (2 \cdot h)$
Outside Diameter of Wheel	$d_{e2}$	mm	$= d_{a2} + m_x$
Normal Pitch	$p_n$	mm	$= \pi \cdot m_n$
Axial Pitch	$p_x$	mm	$= \pi \cdot m_x$
Normal Tooth Thickness in Pitch Circle	$s_n$	mm	$= s_x \cdot \cos \lambda$
Transverse Tooth Thickness in Pitch Circle	$s_x$	mm	$= (p_x / 2)$

### Quality

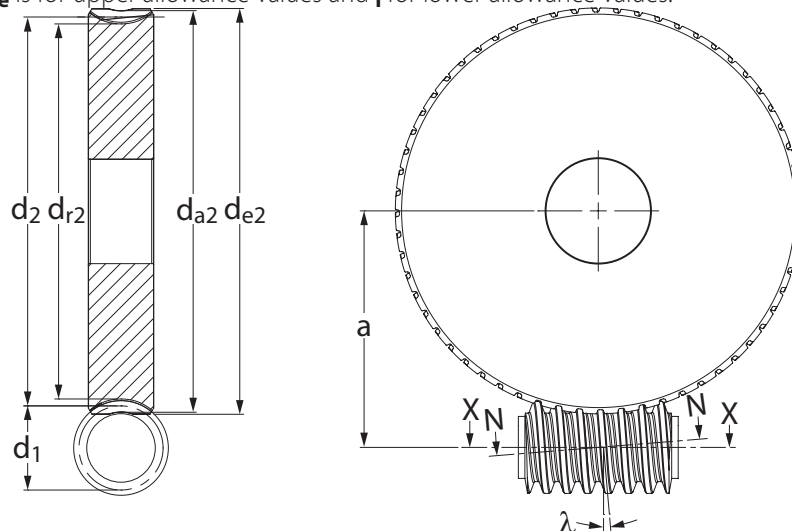
Steel and Stainless Steel worm = Quality 6, DIN 3974. Bronze wormwheel = Quality 7, DIN 3974.  
PEEK and Delrin worms = Quality 7, DIN 3974. PEEK and Delrin wormwheel = Quality 8, DIN 3974.

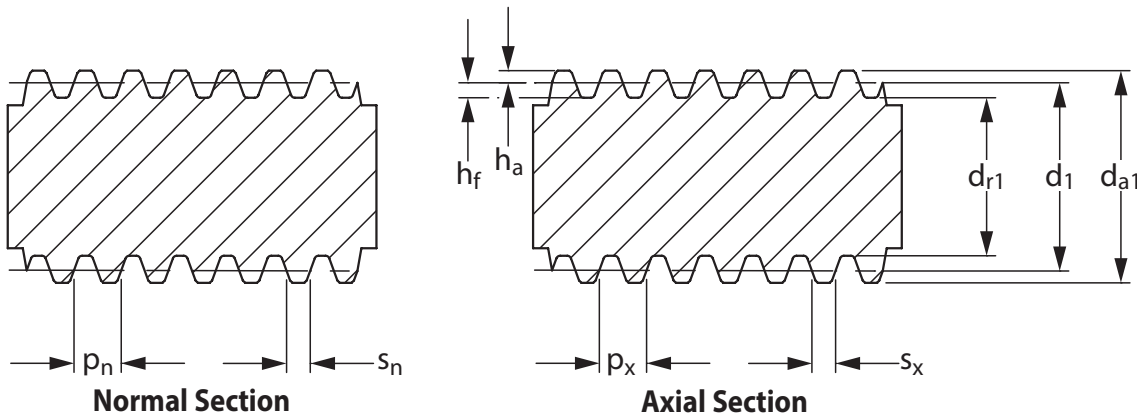
When working with a gear set, the subscript **1** denotes a worm and **2** a wormwheel.

Tip diameter is the theoretical diameter of the gear without tooth thickness tolerance applied.

For  $s_n$  &  $s_x$  when  $x =$  zero, this is the theoretical tooth thickness. Actual tooth thickness will be less.

The subscript **e** is for upper allowance values and **i** for lower allowance values.





### Torque

Stated value is maximum torque based on lowest figure from surface durability, tooth root strength or wear. Values for bronze and cast iron wheel are for matching with steel 817M40 worm.

Value is output torque ( $T_2$ ) at wheel.

Tooth root failure of teeth on wheel before teeth of worm is assumed.

Other factors including worm shaft deflection, duty cycle and temperature will affect maximum allowable torque and service life. Wear is dependant on lubrication.

We recommend that each user compute their own values based on actual operating conditions and test in application.

	Delrin POM	PEEK GF30®
Maximum torque as % of CA104 Aluminium Bronze Wheel	50%*	55 - 65%*
Maximum Wheel Temperature	60°C	80°C

\* Approximate value based on plastic wheel running with steel worm to allow initial selection. Testing in application will be required.

Torque for anti backlash wormwheel gears is limited by the spring rating. Please contact our Technical department for details.

When selecting gears application factors should be applied to required torque.

$$T_2 > T_{\text{required}} \times K_a \quad \text{Application factor } K_a$$

Working characteristics of driving machine	Working characteristics of driven machine			
	Uniform	Light Shocks	Moderate Shocks	Heavy Shocks
Uniform	1.00	1.25	1.50	1.75
Light Shocks	1.10	1.35	1.60	1.85
Moderate Shocks	1.25	1.50	1.75	2.00
Heavy Shocks	1.50	1.75	2.00	2.25+



## Efficiency

The following allows an approximate value for the efficiency of the gears to be found allowing required input torque and gear forces to be calculated. Efficiency is dependant on lubrication and the figures below do not include bearing, seal and other losses.

$$\eta = \tan \lambda / \tan (\lambda + \rho z)$$

$$\rho z = \arctan (\mu)$$

$$v_g = (d_1 \cdot n_1) / (19098 \cdot \cos \lambda)$$

$$T_1 = (T_2 / u) * \eta$$

$T_1$  = Input Torque (Nm)

$T_2$  = Output Torque (Nm)

$u$  = Ratio

$\eta$  = Efficiency

$\lambda$  = Lead Angle (degrees)

$\mu$  = Coefficient of Friction

$\rho z$  = Angle of Friction

$v_g$  = Sliding Velocity (m/s)

$n_1$  = rpm of Worm

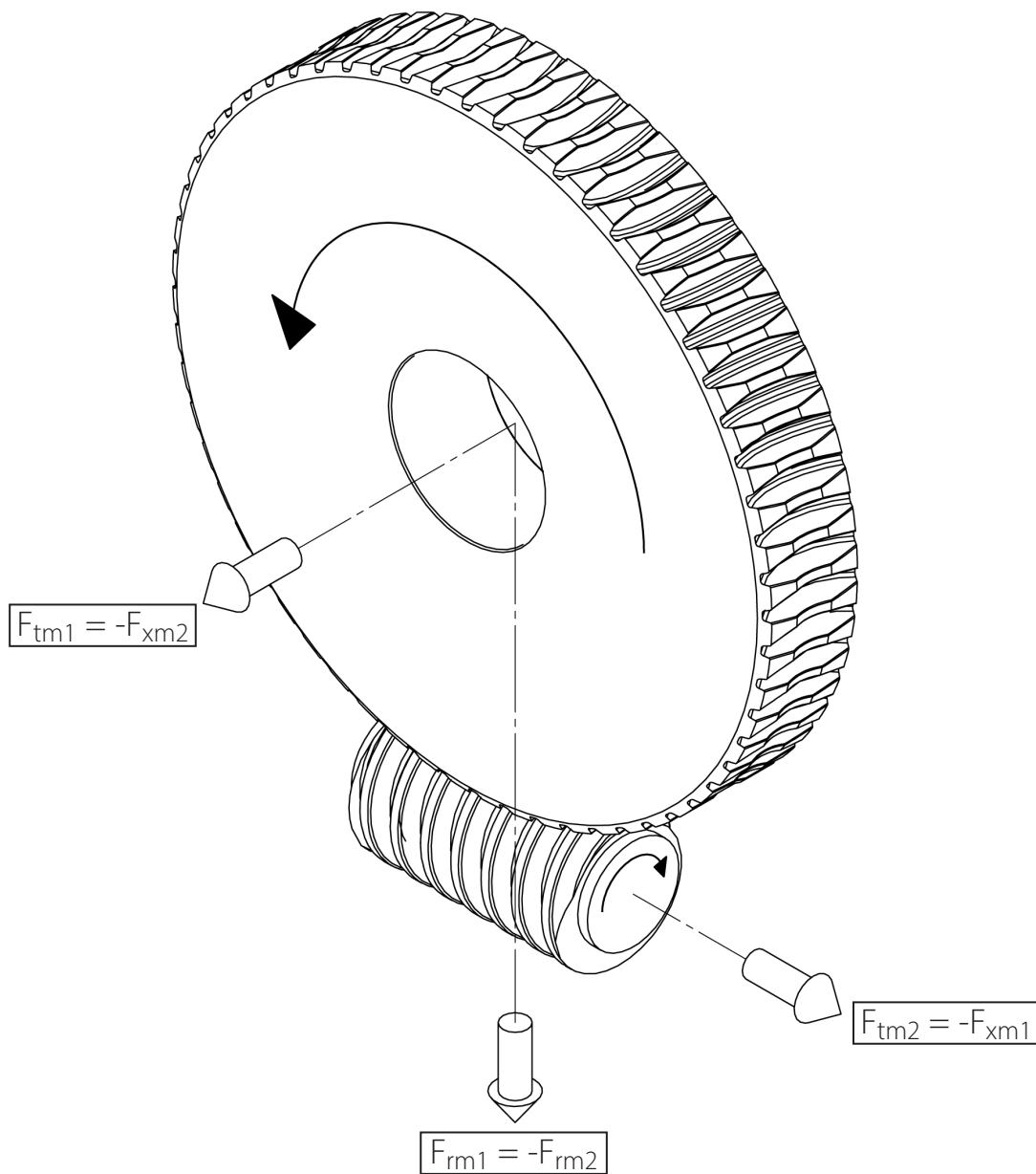
$d_1$  = Reference Diameter of Worm (mm)

## Coefficient of friction $\mu$ (Mineral Oil)

Velocity Range (m/s)	$\mu$ for Velocities 0-30m/s									
	0	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9
0.0-0.9	0.1500	0.0803	0.0694	0.0623	0.0583	0.0543	0.0521	0.0500	0.0480	0.0459
1.0-1.9	0.0438	0.0423	0.0410	0.0396	0.0382	0.0369	0.0359	0.0352	0.0344	0.0336
2.0-2.9	0.0329	0.0322	0.0316	0.0309	0.0304	0.0297	0.0293	0.0289	0.0286	0.0280
3.0-3.9	0.0276	0.0272	0.0268	0.0265	0.0261	0.0257	0.0254	0.0251	0.0248	0.0245
4.0-4.9	0.0242	0.0239	0.0236	0.0234	0.0232	0.0229	0.0226	0.0224	0.0223	0.0221
5.0-5.9	0.0219	0.0217	0.0215	0.0214	0.0212	0.0210	0.0209	0.0207	0.0205	0.0203
6.0-6.9	0.0202	0.0200	0.0199	0.0197	0.0196	0.0194	0.0193	0.0192	0.0190	0.0189
7.0-7.9	0.0187	0.0186	0.0185	0.0184	0.0183	0.0182	0.0181	0.0179	0.0178	0.0177
8.0-8.9	0.0176	0.0175	0.0174	0.0173	0.0173	0.0172	0.0172	0.0170	0.0169	0.0169
9.0-9.9	0.0169	0.0168	0.0166	0.0166	0.0164	0.0164	0.0164	0.0163	0.0162	0.0162
10.0-10.9	0.0161	0.0160	0.0159	0.0159	0.0159	0.0158	0.0157	0.0156	0.0156	0.0156
11.0-11.9	0.0155	0.0154	0.0154	0.0153	0.0153	0.0152	0.0151	0.0151	0.0150	0.0150
12.0-12.9	0.0149	0.0149	0.0149	0.0148	0.0148	0.0147	0.0147	0.0147	0.0146	0.0146
13.0-13.9	0.0146	0.0146	0.0146	0.0145	0.0145	0.0144	0.0144	0.0144	0.0144	0.0144
14.0-14.9	0.0143	0.0143	0.0143	0.0142	0.0142	0.0142	0.0142	0.0142	0.0141	0.0141
15.0-15.9	0.0141	0.0141	0.0141	0.0140	0.0140	0.0139	0.0139	0.0139	0.0139	0.0139
16.0-16.9	0.0139	0.0138	0.0138	0.0138	0.0138	0.0138	0.0137	0.0137	0.0137	0.0137
17.0-17.9	0.0137	0.0136	0.0136	0.0136	0.0136	0.0136	0.0135	0.0135	0.0135	0.0135
18.0-18.9	0.0135	0.0134	0.0134	0.0134	0.0134	0.0134	0.0134	0.0134	0.0134	0.0134
19.0-19.9	0.0134	0.0133	0.0133	0.0133	0.0133	0.0133	0.0132	0.0132	0.0132	0.0132
20.0-20.9	0.0132	0.0131	0.0131	0.0131	0.0131	0.0131	0.0131	0.0131	0.0131	0.0131
21.0-21.9	0.0131	0.0130	0.0130	0.0130	0.0130	0.0130	0.0130	0.0130	0.0130	0.0130
22.0-22.9	0.0130	0.0129	0.0129	0.0129	0.0129	0.0129	0.0129	0.0129	0.0129	0.0129
23.0-23.9	0.0129	0.0129	0.0128	0.0128	0.0128	0.0128	0.0128	0.0128	0.0128	0.0128
24.0-24.9	0.0128	0.0128	0.0127	0.0127	0.0127	0.0127	0.0127	0.0127	0.0127	0.0127
25.0-25.9	0.0127	0.0127	0.0126	0.0126	0.0126	0.0126	0.0126	0.0126	0.0126	0.0126
26.0-26.9	0.0126	0.0126	0.0125	0.0125	0.0125	0.0125	0.0125	0.0125	0.0125	0.0125
27.0-27.9	0.0125	0.0125	0.0124	0.0124	0.0124	0.0124	0.0124	0.0124	0.0124	0.0124
28.0-28.9	0.0124	0.0124	0.0124	0.0124	0.0124	0.0124	0.0124	0.0124	0.0123	0.0123
29.0-29.9	0.0123	0.0123	0.0123	0.0123	0.0123	0.0123	0.0123	0.0123	0.0123	0.0123
30.0	0.0123	-	-	-	-	-	-	-	-	-

Example: if  $V_g = 1.2$  then  $\mu = 0.0410$

## Gear Forces and Direction of Rotation



$$F_{tm1} = 2000 * (T_1 / d_1) = -F_{xm2}$$

$$F_{tm2} = 2000 * (T_2 / d_2) = -F_{xm1}$$

$$F_{rm1} = F_{tm1} * [\tan 2\theta / (\sin \lambda + p_z)] = -F_{rm2}$$

$$p_z = \arctan(\mu)$$

$F_{tm}$  = Tangential force (N)

$F_{xm}$  = Axial force (N)

$F_{rm}$  = Radial force (N)

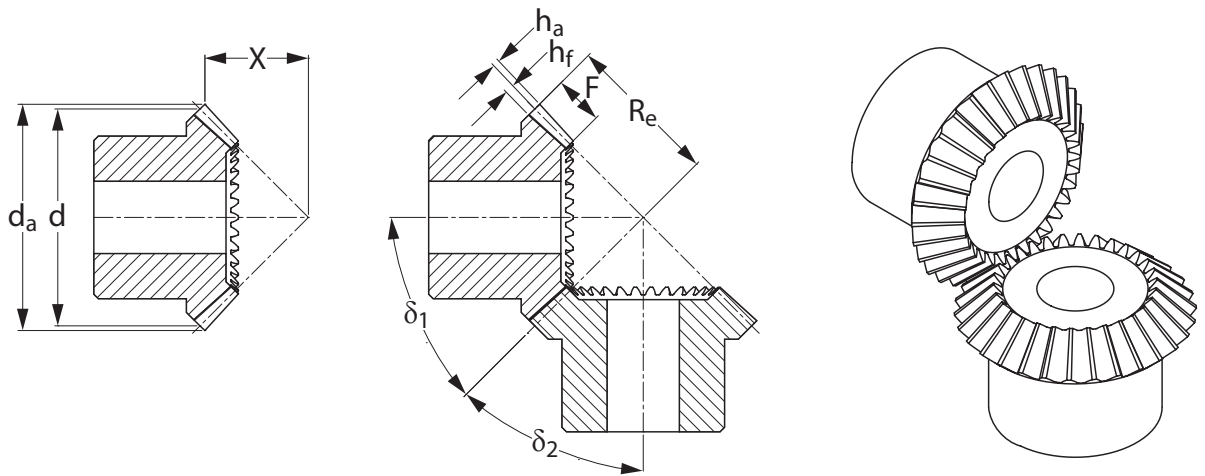
When working with a gear set, the subscript **1** denotes a worm and **2** a wormwheel.

Ondrives worm and wheel gears are supplied right hand lead as standard.

The arrows show the direction of rotation.

Description	Symbol	Unit	Equation
Normal Module	$m_n$		
Pressure Angle	$\alpha$	degrees	$= 20^\circ$
Shaft Angle	$\Sigma$	degrees	$= (90^\circ \text{ for Ondrives standard gears})$
Number of Teeth	$z_1, z_2$		
Gear Ratio	$u$		$= z_2 / z_1$
Pitch Diameter of Worm	$d_1, d_2$	mm	$= z \cdot m_n$
Pitch Cone Angle	$\delta_1$	degrees	$= \delta_1 = \tan^{-1}(\sin \Sigma / (u + \cos \Sigma))$
Pitch Cone Angle	$\delta_2$	degrees	$= \delta_2 = \Sigma - \delta_1$
Cone Distance	$R_e$	mm	$= d_2 / 2 \sin \delta_2$
Addendum	$h_a$	mm	$= 1.00 \cdot m_n$ (for Ondrives standard gears)
Dedendum	$h_f$	mm	$0.6 \text{ to } 1.0m_n = 1.25 \cdot m_n$ (standard gears)
			$1.5 \text{ to } 2.0m_n = 1.22 \cdot m_n$ (standard gears)
			$4.0m_n = 1.20 \cdot m_n$ (standard gears)
Outside Diameter	$d_a$	mm	$= d + 2 h_a \cdot \cos \delta$
Pitch Apex to Crown	$X$	mm	$= R_e \cos \delta - h_a \sin \delta$

Quality Grade 7 DIN 3965



### Torque

Stated value is maximum torque ( $T_2$ ) based on two identical gears with the same number of teeth running at standard centres. Value is minimum from surface stress or bending stress.

Other factors including duty cycle and temperature will affect maximum allowable torque and service life.

Wear is dependant on lubrication.

We recommend that each user compute their own values based on actual operating conditions and test in application.

Materials	817M40	805M20	303 Stainless	316 Stainless
Input Speed	100 rpm Uniform, 12 hours running per day			
Bending Stress Factor $S_b$	32,000	50,000	20,000	15,800
Surface Stress Factor $S_c$	3,000	11,000	1,800	1,400

# ondrives

Precision Gears **Materials**

Ondrives can manufacture gears in a range of additional materials including bronzes, engineering plastics, special steels and stainless steels.

Gears can be heat treated by a range of methods to improve performance.

Please contact our Technical sales team who will be happy to discuss your specific requirements.

Material		Density (Kg/m <sup>3</sup> )	Elongation after Fracture	Tensile Strength (N/mm <sup>2</sup> )	0.2% Proof Stress (N/mm <sup>2</sup> )
<b>805M20</b>	Case Hardened	7,850	11%	980	785
<b>817M40T</b>		7,850	5 - 13%	850 - 100	680
<b>080M40</b>		7,850	7 - 17%	510 - 600	340
<b>722M24T</b>	Nitride Hardened	7,850	13%	850 -1000	650
<b>303S21</b>	Cold Drawn	8,000	35 - 45%	480 - 510	180 - 200
<b>316S16</b>	Cold Drawn	8,000	40%	515	205
<b>17-4PH</b>	Condition A	7,780	10%	1103	100
<b>CA104</b>		7,580	15%	750	430
<b>PB2</b>	Sand Cast	8,600	5%	360 - 500	170 - 280
<b>Brass CZ121</b>		8,470	20%	410	200
<b>PEEK GF30</b>		1,490	2.7%	156	-
<b>Delrin POM</b>		1,410	30%	67	-
<b>Cast Iron GG25</b>	Continuous Cast	7,200	-	145 - 195	-
<b>Titanium Ti-6AL-4V</b>	Grade 5	4,420	10 - 18%	895 -1000	828 - 910

## Material Equivalents

B.S. 970	En	DIN	Werkstoff	SAE/AISI
<b>817M40T</b>	24T	40NiCrMo8-4 / 34CrNiMo6	1.6562, 1.6582	4340, 4337
<b>805M20</b>	362	20NiCrMo2-2 / 20NiCrMo2	1.6523	8620
<b>303S21</b>	58	X10CrNiS189	1.4305	303
<b>316S16</b>	58J	X5CrNiMo17133	1.4436	316
<b>080M40</b>	8	C40	1.0511	1040
<b>655M13</b>	36	14NiCr14	1.5752	3415, 3310, 9314
<b>722M24</b>	40B	32CrMo12	1.7361	-

	ISO	DIN	SAE/AISI
<b>PB2</b>	Cu89Sn11	CuSn12	SAE 64
<b>CA104</b>	GZ-CuAL10Ni	CuAL10Ni	ASTM B150 UNC C63200
<b>Brass CZ121</b>	CuZn39Pb3	-	UNC C38500

B.S. 1452	En	DIN
<b>Cast Iron 250</b>	EN-GJL-250	DIN 1691 GG25

	B.S.	UNS	Werkstoff	AMS
<b>Titanium Ti-6AL-4V</b>	2TA11	R56400	3.7165	4911/4928

Gear Technical

### Delrin POM (White)

DIN EN ISO 1043-1: POM C | polyacetal comopolymer.

Very good dimensional stability compared to Nylon & Hostaform.

Minimal absorption of moisture.

Good sliding properties.

High wear resistance.

High surface hardness.

High mechanical strength and stiffness compared to Nylon & Hostaform.

Can be in contact with food (FDA).

Delrin gears can be run dry or greased/oiled to improve wear.

### PEEK GF30® (Light Brown)

DIN EN ISO 1043-1: PEEK | polyetheretherketone.

Excellent dimensional stability.

Outstanding high mechanical strength and hardness over a broad temperature range.

Shows only a slight distortion under the impact of mechanical load and high temperature.

Good electrical insulating properties.

Extremely high flame resistance.

Self-extinguishing.

Very low smoke emission in a case of a fire.

Can be run dry for slow speed hand operation.

Gears should be greased/oiled for all other operating conditions.

General Properties		Delrin POM	PEEK GF30®
Density	kg/m <sup>3</sup>	1410	1490
Absorption of Moisture		0.20%	0.14%
<b>Mechanical properties</b>			
Yield Stress/ Tensile Strength	N/mm <sup>2</sup>	67	156
Elongation at Break		30.0%	2.7%
Tensile Modulus of Elasticity	N/mm <sup>2</sup>	2800	9700
Ball Indentation Hardness	N/mm <sup>2</sup>	150	230
Shore - Hardness	Skala D	81	88
Coefficient of Friction against hardened and ground steel (dry)		0.10-0.30	0.38-0.46
<b>Thermal Properties</b>			
Melting Temperature	°C	165	343
Thermal Properties	W / (m · K)	0.31	0.43
Coefficient of Linear Thermal Expansion	10 <sup>-6</sup> K <sup>-1</sup>	110	30
Service Temperature, long term (min.)	°C	-50	-20
Service Temperature, long term (max.)	°C	100	250
Service Temperature, short term	°C	140	310
Heat Deflection Temperature	°C	110	315
<b>Electrical Properties</b>			
Dielectric Constant		3.80	3.20
Dielectric Dissipation Factor		0.002	0.001
Specific Volume Resistivity	Ω · cm	1013	1014
Surface Resistivity	Ω	1013	1013
Comparative Tracking Index (test solution A)		600	175
Dielectric Strength	kV/mm	40	20

The backlash figures given for spur, helical and crossed axis helical gears is the theoretical backlash for two identical gears at standard centre distance to the ISO 286 centre distance tolerance.

It is given as circumferential backlash in mm measured on pitch circle diameter. An upper and lower value is quoted. Theoretical backlash is the difference between tooth thickness without and with tolerance applied.

Backlash is calculated according to DIN 3967

Ondrives can manufacture gears to a wide range of tolerances to suit customer application.

Please contact our Technical Sales team who will be happy to discuss your specific requirements.

### Tooth Thickness Tolerances

Gear Type	Module 0.5 to 0.8	Module 1.0 to 3.0	Centre Distance Tol.
Spur	7e/8e DIN 58405	e25 DIN 3967	Js7
Spur (Skive hobbed)	6e DIN 58405	e25 DIN 3967	Js7
Pinion	7e DIN 58405	e25 DIN 3967	-
Parallel Helical	7e DIN 58405	e25 DIN 3967	Js7
Crossed Axis Helical	7e DIN 58405	e25 DIN 3967	Js8
Worm & Wormwheel	7e/8e DIN 58405	e25 DIN 3967	Js8

Gear Type	Module 0.6 to 4.0
Bevel	7f24 DIN 3965/3967

$A_{sn}$  = Tooth thickness allowance which is the difference between measured gear tooth thickness and theoretical value measured in the normal section.

When working with a pair of gears the subscript **1** and **2** denotes input (drive) and output (driven) gear.

For worm and wheel, **1** relates to the worm and **2** to the wormwheel.

The subscript **e** is for upper allowance and **i** for lower allowance.

$T_{sn}$  = Tooth thickness tolerance measured in the normal section. (mm)

$A_{sne} = S_n - S_{ne}$

$A_{sni} = A_{sne} - T_{sn} = S_n - S_{ni}$

### Circumferential Backlash $j_t$

This is the length of arc on the pitch circle diameter through which each can be rotated whilst the other is held stationary. It is measured in the transverse section.

$$j_t = \frac{A_{sn1} + A_{sn2}}{\cos \beta} + \Delta j_a \quad \text{Units = mm \& degrees}$$

### Normal Backlash $j_n$

This is the shortest distance between the flanks of the gears when the opposite flanks are in contact. It is measured in the transverse section.

For spur, helical, crossed axis helical gear

$$j_n = j_t \cdot \cos \alpha_n \cdot \cos \beta \quad \text{Units = mm \& degrees}$$

### Change in Circumferential due to Centre Distance Tolerance $\Delta j_a$

$$\Delta j_a = 2 \cdot A_s \cdot \frac{\tan \alpha_n}{\cos \beta} \quad \text{Units = mm \& degrees}$$

Spur Gear		Parallel Helical Gear		Crossed Axis Helical Gear	
Deviation from Centre Distance $A_s$ (mm)	Change in Backlash $\Delta j_a$ (mm)	Deviation from Centre Distance $A_s$ (mm)	Change in Backlash $\Delta j_a$ (mm)	Deviation from Centre Distance $A_s$ (mm)	Change in Backlash $\Delta j_a$ (mm)
0.001	0.001	0.001	0.001	0.001	0.001
0.010	0.007	0.010	0.008	0.010	0.010
0.015	0.011	0.015	0.011	0.015	0.015
0.020	0.015	0.020	0.015	0.020	0.021
0.025	0.018	0.025	0.019	0.025	0.026
0.030	0.022	0.030	0.023	0.030	0.031
0.035	0.025	0.035	0.026	0.035	0.036
0.040	0.029	0.040	0.030	0.040	0.041
0.045	0.033	0.045	0.034	0.045	0.046
0.050	0.036	0.050	0.038	0.050	0.051

### Angular Backlash $j_{\theta}$

$$j_{\theta} = \frac{360 \times j_i}{\pi \times d_2} \quad \text{Units = mm \& degrees}$$

$d_2$  = Reference diameter (mm)

$A_s$  = Centre distance tolerance (i.e.  $a = 30\text{mm Js7}$ ,  $A_s = \pm 0.0105\text{mm}$ )

$\alpha_n$  = Normal pressure angle ( $\alpha_n = 20^\circ$ )

$\beta$  = Helix angle ( $\beta = \text{zero}$  for spur gears)

Replace helix angle  $\beta$  with lead angle  $\lambda$  for worm and wheel.

$1^\circ = 60$  arc minutes

### e25 DIN 3967

Reference Diameter d (mm) Over Upto	Upper Tooth Thickness Allowance $A_{sne}$	Tooth Thickness Tolerance $T_{sn}$
- 10	-0.022mm	0.020mm
10 50	-0.030mm	0.030mm
50 125	-0.040mm	0.040mm
125 280	-0.056mm	0.050mm

### 7e DIN 58405

Reference Diameter d (mm)	Normal Module $m_{sn}$	Upper Tooth Thickness Allowance $A_{sne}$	Tooth Thickness Tolerance $T_{sn}$
from 3 to 6	>0.16 to 0.25	0.028	0.011
	>0.25 to 0.6	0.030	0.012
	>0.6 to 1.6	0.035	0.014
>6 to 12	>0.16 to 0.25	0.030	0.012
	>0.25 to 0.6	0.035	0.014
	>0.6 to 1.6	0.040	0.016
>12 to 25	>0.16 to 0.25	0.035	0.014
	>0.25 to 0.6	0.040	0.016
	>0.6 to 1.6	0.045	0.018
	>1.6 to 3	0.050	0.020
>25 to 50	>0.16 to 0.25	0.040	0.016
	>0.25 to 0.6	0.045	0.018
	>0.6 to 1.6	0.050	0.020
	>1.6 to 3	0.055	0.022
>50 to 100	>0.16 to 0.25	0.045	0.018
	>0.25 to 0.6	0.050	0.020
	>0.6 to 1.6	0.055	0.022
	>1.6 to 3	0.063	0.024
>100 to 200	>0.6 to 1.6	0.063	0.024
	>1.6 to 3	0.070	0.029
>200 to 400	>0.6 to 1.6	0.070	0.029
	>1.6 to 3	0.080	0.032

\* $A_{sne}$  is converted from base tangent length allowance ( $A_w$ ) according to  $A_w = A_{sn} * \cos 20^\circ$

### Example for Calculating Backlash for Two Non-Identical Gears

Input Gear PSG0.5-20 7e

Output Gear PSG0.5-40 7e

1. Calculate the reference diameter  $d$  for each gear

$$\text{PSG0.5-20 } d_1 = z \cdot m_n = 10.00\text{mm}$$

$$\text{PSG0.5-40 } d_2 = 20.00\text{mm}$$

2. Find  $A_{sne}$  and  $T_{sn}$  from the tables overleaf

$$\text{PSG0.5-20 } A_{sne} = -0.035\text{mm } T_{sn} = -0.014\text{mm}$$

$$\text{PSG0.5-40 } A_{sne} = -0.040\text{mm } T_{sn} = -0.016\text{mm}$$

3. Calculate  $A_{sni}$  for each gear

$$\text{PSG0.5-20 } A_{sni} = A_{sne} - T_{sn} = -0.035 - 0.014 = -0.021\text{mm}$$

$$\text{PSG0.5-40 } A_{sni} = A_{sne} - T_{sn} = -0.040 - 0.016 = -0.024\text{mm}$$

4. Calculate the centre distance of the two gears and the centre distance tolerance

$$\text{centre distance} = (10 + 20) / 2 = 15\text{mm}$$

$$J_{s7} = \pm 0.009\text{mm}$$

5. Calculate the change in backlash due to centre distance

$$\Delta j_a = 2 \cdot A_s \cdot \frac{\tan \alpha_n}{\cos \beta} + 2 \cdot 0.009 \cdot \frac{\tan 20}{\cos 0} = 0.007\text{mm}$$

6. Calculate the maximum backlash

Remove the minus sign on  $A_{sn}$

$$j_t = \frac{A_{sne1} + A_{sne2}}{\cos \beta} + \Delta j_a = \frac{0.035 + 0.040}{\cos 0} + 0.007 = 0.082\text{mm}$$

7. Calculate the minimum backlash

Remove the minus sign on  $A_{sn}$

$$j_t = \frac{A_{sni1} + A_{sni2}}{\cos \beta} + \Delta j_a = \frac{0.021 + 0.024}{\cos 0} - 0.007 = 0.038\text{mm}$$

8. Convert to angular backlash

$$j_\theta = \frac{360 \times j_t}{\pi \times d_2} \quad 1^\circ = 60 \text{ arc minutes}$$

$$j_\theta = 28.208 \text{ to } 13.072 \text{ arc minutes}$$



### Hole Sizes (mm)

<b>Over</b>	3	6	10	18	30	40	50	65	80	100	120	140	160	180	200	225
<b>Inc.</b>	6	10	18	30	40	50	65	80	100	120	140	160	180	200	225	250

### Micrometres (10<sup>-3</sup>m)

<b>F6</b>	18	22	27	33	41	49	58	68	79
	10	13	16	20	25	30	36	43	50
<b>F7</b>	22	28	34	41	50	60	71	83	96
	10	13	16	20	25	30	36	43	50
<b>G6</b>	12	14	17	20	25	29	34	39	44
	4	5	6	7	9	10	12	14	15
<b>G7</b>	16	20	24	28	34	40	47	54	61
	4	5	6	7	9	10	12	14	15
<b>H6</b>	8	9	11	13	16	19	22	25	29
	0	0	0	0	0	0	0	0	0
<b>H7</b>	12	15	18	21	25	30	35	40	46
	0	0	0	0	0	0	0	0	0
<b>H8</b>	18	22	27	33	39	46	54	63	72
	0	0	0	0	0	0	0	0	0
<b>H9</b>	30	36	43	52	62	74	87	100	115
	0	0	0	0	0	0	0	0	0
<b>H10</b>	48	58	70	84	100	120	140	160	185
	0	0	0	0	0	0	0	0	0
<b>H11</b>	75	90	110	130	160	190	220	250	290
	0	0	0	0	0	0	0	0	0
<b>J6</b>	5	5	6	8	10	13	16	18	22
	-3	-4	-5	-5	-6	-6	-6	-7	-7
<b>J7</b>	6	8	10	12	14	18	22	26	30
	-6	-7	-8	-9	-11	-12	-13	-14	-16
<b>J8</b>	10	12	15	20	24	28	34	41	47
	-8	-10	-12	-13	-15	-18	-20	-22	-25
<b>JS6</b>	4	4.5	5.5	6.5	8	9.5	11	12.5	14.5
	-4	-4.5	-5.5	-6.5	-8	-9.5	-11	-12.5	-14.5
<b>JS7</b>	6	7.5	9	10.5	12.5	15	17.5	20	23
	-6	-7.5	-9	-10.5	-12.5	-15	-17.5	-20	-23
<b>JS8</b>	9	11	13.5	16.5	19.5	23	27	31.5	36
	-9	-11	-13.5	-16.5	-19.5	-23	-27	-31.5	-36
<b>K6</b>	2	2	2	2	3	4	4	4	5
	-6	-7	-9	-11	-13	-15	-18	-21	-24
<b>M6</b>	-1	-3	-4	-4	-4	-5	-6	-8	-8
	-9	-12	-15	-17	-20	-24	-28	-33	-37
<b>M7</b>	0	0	0	0	0	0	0	0	0
	-12	-15	-18	-21	-25	-30	-35	-40	-46

### Hole Sizes (mm)

Over	3	6	10	18	30	40	50	65	80	100	120	140	160	180	200	225
Inc.	6	10	18	30	40	50	65	80	100	120	140	160	180	200	225	250

### Micrometres (10<sup>-3</sup>m)

<b>f6</b>	-10	-13	-16	-20	-25	-30	-36	-43	-50
	-18	-22	-27	-33	-41	-49	-58	-68	-79
<b>f7</b>	-10	-13	-16	-20	-25	-30	-36	-43	-50
	-22	-28	-34	-41	-50	-60	-71	-83	-96
<b>g5</b>	-4	-5	-6	-7	-9	-10	-12	-14	-15
	-9	-11	-14	-16	-20	-23	-27	-32	-35
<b>g6</b>	-4	-5	-6	-7	-9	-10	-12	-14	-15
	-12	-14	-17	-20	-25	-29	-34	-39	-44
<b>g7</b>	-4	-5	-6	-7	-9	-10	-12	-14	-15
	-16	-20	-24	-28	-34	-40	-47	-54	-61
<b>h6</b>	0	0	0	0	0	0	0	0	0
	-8	-9	-11	-13	-16	-19	-22	-25	-29
<b>h7</b>	0	0	0	0	0	0	0	0	0
	-12	-15	-18	-21	-25	-30	-35	-40	-46
<b>h8</b>	0	0	0	0	0	0	0	0	0
	-18	-22	-27	-33	-39	-46	-54	-63	-72
<b>h9</b>	0	0	0	0	0	0	0	0	0
	-30	-36	-43	-52	-62	-74	-87	-100	-115
<b>h10</b>	0	0	0	0	0	0	0	0	0
	-48	-58	-70	-84	-100	-120	-140	-160	-185
<b>h11</b>	0	0	0	0	0	0	0	0	0
	-75	-90	-110	-130	-160	-190	-220	-250	-290
<b>j6</b>	6	7	8	9	11	12	13	14	16
	-2	-2	-3	-4	-5	-7	-9	-11	-13
<b>j7</b>	8	10	12	13	15	18	20	22	25
	-4	-5	-6	-8	-10	-12	-15	-18	-21
<b>js5</b>	2.5	3	4	4.5	5.5	6.5	7.5	9	10
	-2.5	-3	-4	-4.5	-5.5	-6.5	-7.5	-9	-10
<b>js6</b>	4	4.5	5.5	6.5	8	9.5	11	12.5	14.5
	-4	-4.5	-5.5	-6.5	-8	-9.5	-11	-12.5	-14.5
<b>js7</b>	6	7.5	9	10.5	12.5	15	17.5	20	23
	-6	-7.5	-9	-10.5	-12.5	-15	-17.5	-20	-23
<b>k6</b>	9	10	12	15	18	21	25	28	33
	1	1	1	2	2	2	3	3	4
<b>m6</b>	12	15	18	21	25	30	35	40	46
	4	6	7	8	9	11	13	15	17
<b>m7</b>	16	21	25	29	34	41	48	55	63
	4	6	7	8	9	11	13	15	17

Bore Size d Over	Bore Size d Including	Keyway Size b x h	Pin Hole	Tapped Hole
-	6	-	1.5	M3 x 0.5
6	8	2 x 2	2.0	M3 x 0.5
8	10	3 x 3	3.0	M3 x 0.5
10	12	4 x 4	4.0	M4 x 0.7
12	17	5 x 5	5.0	M5 x 0.8
17	22	6 x 6	6.0	M6 x 1.0
22	30	8 x 7	8.0	M8 x 1.25
30	38	10 x 8	10.0	M10 x 1.5
38	44	12 x 8	10.0	M10 x 1.5
44	50	14 x 9	10.0	M12 x 1.75

Keyways to DIN 6885 Js9 sliding fit. D10 free fit and P9 tight fit available on request.

Woodruff keyways available on request.

Standard bore tolerance H7 ISO 286. Other tolerances available.

Special bore shapes available including square and hexagon.

Key b x h	Width		Depth				Radius r Max - Min
	Shaft b N9	Bore b Js9	Shaft t <sub>1</sub>		Bore t <sub>1</sub>		
			Nominal	Tolerance	Nominal	Tolerance	
2 x 2	-0.004/-0.029	+0.012/-0.012	1.2	+0.10/-0.00	1.0	+0.10/-0.00	0.16 - 0.08
3 x 3	-0.004/-0.029	+0.012/-0.012	1.8	+0.10/-0.00	1.4	+0.10/-0.00	0.16 - 0.08
4 x 4	+0.000/-0.030	+0.015/-0.015	2.5	+0.10/-0.00	1.8	+0.10/-0.00	0.16 - 0.08
5 x 5	+0.000/-0.030	+0.015/-0.015	3.0	+0.10/-0.00	2.3	+0.10/-0.00	0.25 - 0.16
6 x 6	+0.000/-0.030	+0.015/-0.015	3.5	+0.10/-0.00	2.8	+0.10/-0.00	0.25 - 0.16
8 x 7	+0.000/-0.036	+0.018/-0.018	4.0	+0.20/-0.00	3.3	+0.20/-0.00	0.25 - 0.16
10 x 8	+0.000/-0.036	+0.018/-0.018	5.0	+0.20/-0.00	3.3	+0.20/-0.00	0.40 - 0.25
12 x 8	+0.000/-0.043	+0.021/-0.021	5.0	+0.20/-0.00	3.3	+0.20/-0.00	0.40 - 0.25

